// smart dustbin project

#include <Servo.h> //servo library

Servo servo;

int trigPin = 5;

int echoPin = 6;

int servoPin = 7;

int led= 10;

long duration, dist, average;

long aver[3]; //array for average

void setup() {

Serial.begin(9600);

servo.attach(servoPin);

pinMode(trigPin, OUTPUT);

pinMode(echoPin, INPUT);

servo.write(0); //close cap on power on

delay(100);

servo.detach();

}

void measure() {

digitalWrite(10,HIGH);

digitalWrite(trigPin, LOW);

delayMicroseconds(5);

digitalWrite(trigPin, HIGH);

delayMicroseconds(15);

digitalWrite(trigPin, LOW);

pinMode(echoPin, INPUT);

duration = pulseIn(echoPin, HIGH);

dist = (duration/2) / 29.1; //obtain distance

}

void loop() {

for (int i=0;i<=2;i++) { //average distance

measure();

aver[i]=dist;

delay(10); //delay between measurements

}

dist=(aver[0]+aver[1]+aver[2])/3;

if ( dist<50 ) {

//Change distance as per your need

servo.attach(servoPin);

delay(1);

servo.write(0);

delay(3000);

servo.write(150);

delay(1000);

servo.detach();

}

Serial.print(dist);

}